## LINEAR MOTORS

	Sizi	ng Form		
Customer Name /		Filling Date(DD/MM/YEAR) /		
Contact Person /		Telephone /		
-mail /		Fax /		
3. Point-to-Point Motion wit Property: Specific travel dis Application: Pick and plac	stance in specific			
a. Known Motion Cc	a. Known Motion Condition Velocity			
(1) Load Mass	kg	A		
(2) Effective Stroke	m	÷ •		
(3) Acceleration	m/s <sup>2</sup>			
(4) Dwell Time	S			
		Stroke		
b. Driver Condi	lion	Moving Time — Dwell Time - Time		
(1) Max. Output Voltage	V			
(2) Continuous Current	A	Cycle Period / 2		
(3) Peak Current	A			
c. Encoder		f. Motion Direction		

c. Encoder			
(1)	🗆 Analog	🗆 Digita	I
(2)	Resolution		μm

d. Working Environment			
(1)	(1) 🗌 Room Temperature		
(2) □ Constant Temperature°C			
(3)	Vacuum Torr		
(4)	Clean Room Level		

	e. Motion Precision	
(1)	Positioning Accuracy	μm
(2)	Repetitive Accuracy	μm

f. Motion Direction			
(1)	Horizontal		
(2)	Vertical		
(3)	Tilt Degrees		

	g. Installation Method
(1)	Lying Flat
(2) 🗌	Vertically standing
(3)	Wall Mount

h. Space Restrictions			
(1) 🗌 None			
(2) 🗆 Yes _	mm x	mm x	_mm